

Problems in Mathematics & Experiments with Mathematica

5. Indefinite integral

5.3 Find a particular antiderivative

Theory

• Method

Let an antiderivative $F_1(x)$ be known, and let the point (x_0, y_0) be given. Find the antiderivative $F_2(x)$ for which $F_2(x_0) = y_0$. Since $F_2(x) = F_1(x) + C$, we obtain

$$F_2(x) = F_1(x) + y_0 - F_1(x_0)$$

Exercises and problems

■ Mathematica initialization

```
SetDirectory["FileName" /.
  NotebookInformation[EvaluationNotebook[]] /.
  Which[
    $System == "Microsoft Windows",
      FrontEnd`FileName[{_, d___}, nam_, ___] :>
    ToFileName[{d}] ,
    $System != "Microsoft Windows", FrontEnd`FileName[
      d_List, nam_, ___] :> ToFileName[d] ]];

<< "package//slopeprt.m"
<< package//npow.m;
Abs'[x_] := Which[x < 0, -1, x > 0, 1, True, 0];
Sign'[x_] := 0;
```

SOLVED PROBLEM 5.3.1

For the given $f(x)$, find the antiderivative for which $F_2(x_0) = y_0$.

$$f(x) := \frac{1}{2}x^2 - 3; \{x_0, y_0\} = \{1, 2\};$$

◦ SOLUTION

An antiderivative is

$$G(u) := \int f(v) dv /. v \rightarrow u$$

Now, the needed one is

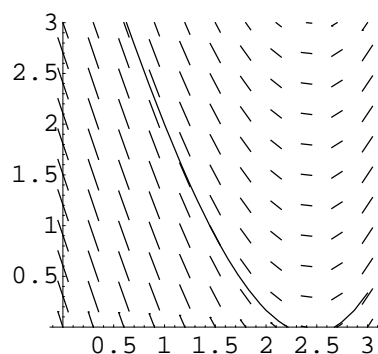
$$F[u] := G[u] + y_0 - G[x_0]$$

Plot the slope portrait and $F(x)$:

```
slp = SlopePortrait[{1, f[x]}, {x, 0., 3., 0.3}, {y, 0, 3, 0.3}];
```

```
plt = Plot[F[x], {x, 0, 3},
  DisplayFunction -> Identity];
```

```
plt1 = Show[Graphics[slp], plt,
  DisplayFunction -> $DisplayFunction,
  AspectRatio -> Automatic,
  Axes -> True, PlotRange -> {0, 3}];
```



◦

PROBLEM 5.3.2

The speed of a process $F(t)$ is the known function $v(t)$. Find $F(t)$ if $F(t_0) = F_0$.

- (1) $t_0 = 0; F_0 = 0.1; v(t) := 2^t$;
- (2) $t_0 = 0; F_0 = 2; v(t) := 3 \cdot 2^{-t}$;
- (3) $t_0 = 0; F_0 = 1; v(t) := \log_2(t + 1)$;
- (4) $t_0 = 0; F_0 = 1; v(t) := \sin(3t)$;
- (5) $t_0 = 2; F_0 = 3; v(t) := t e^{-t^2}$;

PROBLEM 5.3.3 Motion of a body

The acceleration of a motion $s(t)$ is the known function $a(t)$. Find $s(t)$ if $s(t_0) = s_0$ and $v(t_0) = v_0$.

$$(1) \quad t_0 = 0; \quad v_0 = 0.1; \quad s_0 = 1; \quad a(t_) := 2^{-t};$$

$$(2) \quad t_0 = 0; \quad v_0 = 0; \quad s_0 = 2; \quad a(t_) := 2;$$

$$(3) \quad t_0 = 0; \quad v_0 = 1; \quad s_0 = 1; \quad a(t_) := \sin(t);$$

$$(4) \quad t_0 = 2; \quad v_0 = 2; \quad s_0 = 0; \quad a(t_) := 1 - 3^{-t};$$
